Assumptions 000000 Implementation 0000000000

Review of OLS

Week 2 POLS 8830: Advanced Quantitative Methods

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The Classic Regression Equation

• Assume the following equation to be true for the population:

$$Y_i = \beta_1 + \beta_2 X_{2i} + \ldots + \beta_k X_{ki} + \epsilon_i \tag{1}$$

• Which we can rewrite as a series of equations:

$$Y_{1} = \beta_{1} + \beta_{2}X_{21} + \beta_{3}X_{31} + \ldots + \beta_{k}X_{k1} + \epsilon_{1}$$

$$Y_{2} = \beta_{1} + \beta_{2}X_{22} + \beta_{3}X_{32} + \ldots + \beta_{k}X_{k2} + \epsilon_{2}$$
(2)

$$Y_n = \beta_1 + \beta_2 X_{2n} + \beta_3 X_{3n} + \ldots + \beta_k X_{kn} + \epsilon_n$$

The Classic Regression Equation

 Looking at equation [2], we can see that really all we have here is a matrix:

$$\begin{bmatrix} Y_1 \\ Y_2 \\ \dots \\ Y_n \end{bmatrix} = \begin{bmatrix} 1 & X_{21} & X_{31} & \dots & X_{k1} \\ 1 & X_{22} & X_{32} & \dots & X_{k2} \\ \dots & \dots & \dots & \dots & \dots \\ 1 & X_{2n} & X_{3n} & \dots & X_{kn} \end{bmatrix} \begin{bmatrix} \beta_1 \\ \beta_2 \\ \dots \\ \beta_n \end{bmatrix} \begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \dots \\ \epsilon_n \end{bmatrix}$$
(3)

• Therefore, with no alterative in meaning, we can rewrite equation [1] with the following notation:

$$\mathbf{y} = \mathbf{X}\beta + \epsilon \tag{4}$$

- 1. Linearity
 - The CLRM as specified in the form
 Y_i = β₁ + β₂X_{2i} + ... + β_kX_{ki} + ε_i specifies a linear relationship between y and x₁, x₂,..., x_k.
- 2. Full Rank (No Perfect Multicollinearity)
 - X is an *n* × *k* matrix of rank *K*
 - This means that all columns in **X** are linearly independent and there are at least *K* observations
 - Thus, there are no exact linear relationships

- 3. $E[\epsilon_i | \mathbf{X}] = 0$
 - This assumption implies that the disturbance term should have a conditional expected value of 0 at every observation.
 - For the full set of observations, we can write this as:

$$E[\epsilon | \mathbf{X}] = \begin{bmatrix} E[\epsilon_1 | \mathbf{X}] \\ E[\epsilon_2 | \mathbf{X}] \\ \vdots \\ E[\epsilon_n | \mathbf{X}] \end{bmatrix} = 0$$
(5)

• The assumption in equation [5] is essential, as it implies that: $E[\mathbf{y}|\mathbf{X}] = \mathbf{X}\beta \tag{6}$

4. Spherical Disturbances (Homoscedasticity and Nonautocorrelation)

• Var
$$[\epsilon_i | \mathbf{X}] = \sigma^2$$
, for all $i = 1, \dots, n$,

- and
- $\operatorname{Cov}[\epsilon_i, \epsilon_j | \mathbf{X}] = 0$, for all $i \neq j$
- State that the disturbance terms in the CLRM possess consistant variance and that they are uncorrelated across observations

• Additionally, these assumptions imply that:

$$E[\epsilon\epsilon' | \mathbf{X}] = \begin{bmatrix} E[\epsilon_1\epsilon_1 | \mathbf{X}] & E[\epsilon_1\epsilon_2 | \mathbf{X}] & \dots & E[\epsilon_1\epsilon_n | \mathbf{X}] \\ E[\epsilon_2\epsilon_1 | \mathbf{X}] & E[\epsilon_2\epsilon_2 | \mathbf{X}] & \dots & E[\epsilon_2\epsilon_n | \mathbf{X}] \\ \vdots & \vdots & \vdots & \vdots \\ E[\epsilon_n\epsilon_1 | \mathbf{X}] & E[\epsilon_n\epsilon_2 | \mathbf{X}] & \dots & E[\epsilon_n\epsilon_n | \mathbf{X}] \end{bmatrix}$$
$$= \begin{bmatrix} \sigma^2 & 0 & \dots & 0 \\ 0 & \sigma^2 & \dots & 0 \\ \vdots & \vdots \\ 0 & 0 & \dots & \sigma^2 \end{bmatrix}$$

• Which we neatly summarize as:

$$E[\epsilon \epsilon' | \mathbf{X}] = \sigma^2 \mathbf{I} \tag{7}$$

- 5. Nonstochastic Regressors
- This assumption simply holds that all values in the matrix X are fixed
- In practice, this assumption does not match the reality of social science data where many of our independent variables of theoretical interest are random
- Thus our assumption is more about the data generating process that produces x_i as being fixed

- 6. Normality
 - Here we simply add to the list of assumptions about the disturbances by assuming they are normally distributed
- Formally, we state:

$$\epsilon | \mathbf{X} \sim N[0, \sigma^2 \mathbf{I}]$$
 (8)

Assumptions 000000 Implementation •000000000

Implementation

- Base Packages:
 - glm or lm
 - Generalized linear models, or linear model
- Primary Packages:
 - Imtest
 - Tests and Diagnostics for OLS
 - sandwich
 - Robust standard errors

Implementation: GLM Syntax

- GLM Implementation
 - glm(formula, family = gaussian, data, weights, subset, na.action, start = NULL, etastart, mustart, offset, control = list(...), model = TRUE, method = "glm.fit", x = FALSE, y = TRUE, singular.ok = TRUE, contrasts = NULL, ...)

Implementation: GLM Syntax

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- Main Components:
 - formula: $Y \sim X_1 + X_2 + X_3 ...$
 - family: 'gaussian' for linear regression
 - data: call to your dataframe, list, or environment

Implementation: GLM Implementation

 mRate <- glm(Murder ~ Population + Income + Illiteracy, family = gaussian, data = state)

Implementation: GLM Implementation

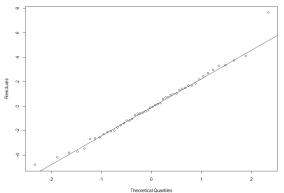
- mRate < glm(Murder \sim Population + Income + Illiteracy, family = gaussian, data = state)
- mRate: glm object
- Murder: Outcome Variable
- Population, Income, Illiteracy: Independent Variables
- state: Data Frame or coercable object
- summary(mRate)

Note: state comes from the **datasets** package built into R.

- 1. Linearity in the relationship under study
- 2. Error term is independently and identically distributed normally about 0 with standard deviation of σ^2
- 3. No perfect multicollinearity between independent variables
- 4. Spherical errors (v_i neither correlated with the independent variables nor one another)

- 1. Linearity in the relationship under study
 - This is generally going to be a theoretical assumption made in model selection
 - Can use a version of scatterplots to check
 - qqnorm(residuals(g/lm object))
 - qqline(residuals(g/lm object))

- 1. Linearity in the relationship under study
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Normal Q-Q Plot

Figure: Sample Q-Q Plot

- 2. Error term is independently and identically distributed normally about 0 with standard deviation of σ^2
 - hist(mRate\$residuals)
 - sd(mRate\$residuals)

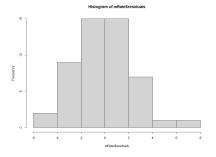


Figure: Distribution of Residuals

Implementation 00000000000

- 3. No perfect multicollinearity between independent variables
 - Three ways correlations, tolerance, variable inflation factor

- 3. No perfect multicollinearity between independent variables
 - Three ways correlations, tolerance, variable inflation factor
 - Correlation

```
• cor.test(IV1, IV2, method = c("pearson",
 "kendall", "spearman"), exact = NULL, conf.level =
 0.95, continuity = FALSE, use = "complete.obs")
```

- 3. No perfect multicollinearity between independent variables
 - Three ways correlations, tolerance, variable inflation factor
 - Tolerance
 - object=(1-(model\$deviance/model\$null.deviance))

- 3. No perfect multicollinearity between independent variables
- Three ways correlations, tolerance, variable inflation factor
- VIF
 - vif(model)
- Any IV with a vif greater than 10 needs to be addressed; greater than 5 indicates potential issues

- 4. Spherical errors (v_i neither correlated with the independent variables nor one another)
 - Heteroskedasticity: Breusch-Pagan Test
 - bptest(model)
 - coeftest(model, vcov = vcovHC(model, "HC1"))
 - can use sandwich and other SE calculation variants: "HCO", "HC1", "HC2", "HC3", "arellano", etc.

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 - can use sandwich and other SE calculation variants: "HCO", "HC1", "HC2", "HC3", "arellano", etc.
 - Auto/serial correlation: Durbin-Watson Test
 - dwtest(DV \sim IV1 + IV2 + IV3 ...)
 - Significant results indicate the existence of heteroskedastic errors or serial correlation respectively.